

ΘΕΜΑ Α

A1 δ

A2 β

A3 α

A4 γ

A5 α ε

β ε

γ λ

δ λ

ε ε

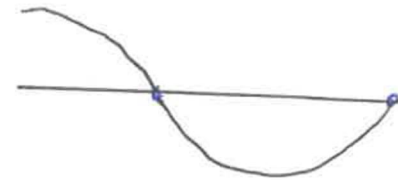
ΘΕΜΑ Β

B1 (iii)

Αprox $L = \frac{3}{4} \lambda_1$

Tαxia $L = \frac{5}{4} \lambda_2$

| \Rightarrow



$$\frac{3}{4} \lambda_1 = \frac{5}{4} \lambda_2 \Rightarrow 3 \nu T_1 = 5 \nu T_2 \Rightarrow \frac{T_1}{T_2} = \frac{5}{3}$$

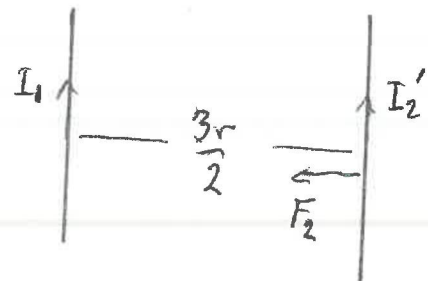
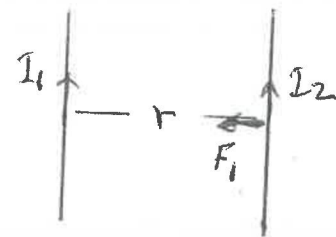
B2 (i)

Αprox $F_1 = \frac{\mu_0}{4\pi} \frac{2I_1 I_2 l}{r}$

Tαxia $F_2 = \frac{\mu_0}{4\pi} \frac{2I_1 I_2' l}{\frac{3r}{2}}$

} \Rightarrow

$$\frac{F_1}{F_2} = \frac{I_2 \cdot 3}{I_2' \cdot 2} = \frac{3I_2}{2I_2' \cdot 2} = \frac{3}{4}$$



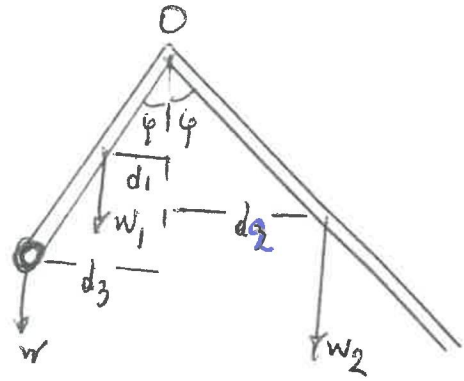
B₃ (ii)

$$\sum \tau_0 = 0 \Rightarrow$$

$$w_1 d_1 + w d_3 - w_2 d_2 = 0 \Rightarrow$$

$$Mg \frac{l_1}{2} \eta \mu \varphi + \frac{M}{2} g l \eta \mu \varphi = Mg \frac{l_2}{2} \eta \mu \varphi \Rightarrow$$

$$\frac{l_1}{2} \cancel{\eta \mu \varphi} + \frac{l}{2} \cancel{\eta \mu \varphi} = \frac{l_2}{2} \cancel{\eta \mu \varphi} \Rightarrow \frac{2 \cdot l_1}{2} = \frac{l_2}{2} \rightarrow \frac{l_1}{l_2} = \frac{1}{2}$$



ΘΕΜΑ Γ

Γ 1. $\lambda' = \lambda + \frac{h}{mc} (1 - \cos \varphi) \Rightarrow \lambda' = 8\lambda_c + \lambda_c (1 - (-1))$

$$\Rightarrow \lambda' = 8\lambda_c + 2\lambda_c \Rightarrow \lambda' = 10\lambda_c$$

$$\lambda_c = \frac{h}{mc} = \frac{hc}{mc^2} = \frac{1200 \text{ eV nm}}{5 \cdot 10^5 \text{ eV}} = 240 \cdot 10^{-5} \text{ nm}$$

$$\Rightarrow \lambda_c = 24 \cdot 10^{-13} \text{ m}$$

όρα $\lambda' = 10\lambda_c = 24 \cdot 10^{-12} \text{ m}$

Γ 2.

$$E_\gamma = hf = h \frac{c}{\lambda} = \frac{hc}{8\lambda_c} = \frac{hc}{8 \frac{h}{mc}} = \frac{1}{8} mc^2$$

$$E'_\gamma = hf' = h \frac{c}{\lambda'} = \frac{hc}{10\lambda_c} = \frac{hc}{10 \frac{h}{mc}} = \frac{1}{10} mc^2$$

$$K_e = E_\gamma - E'_\gamma = \left(\frac{1}{8} - \frac{1}{10} \right) mc^2 = \frac{1}{40} mc^2 \Rightarrow$$

$$K_e = \frac{1}{40} \cdot 5 \cdot 10^5 \text{ eV} \Rightarrow K_e = 12500 \text{ eV}$$

$$\Gamma 3. \text{ i } \text{ i } \text{ i } \text{ i } \text{ i } \quad K = E_{\varphi} - \varphi \Rightarrow K = hf - \varphi$$

$$\text{Принцип } K \geq 0 \Rightarrow hf - \varphi \geq 0 \Rightarrow hf \geq \varphi \Rightarrow$$

$$f \geq \frac{\varphi}{h} \Rightarrow f \geq f_0$$

$$\text{Единица } f_0 = \frac{\varphi}{h} = \frac{1,4 \cdot 1,6 \cdot 10^{-19}}{6,4 \cdot 10^{-34}} \Rightarrow f_0 = 3,5 \cdot 10^{14} \text{ Hz}$$

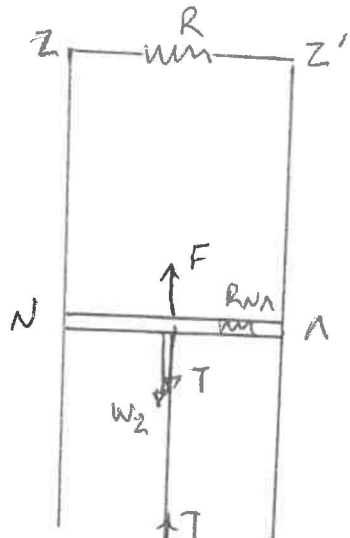
$$\Gamma 4. \quad E_{\varphi} = hf_1 = h \frac{c}{\lambda_1} = \frac{1200 \text{ eV} \cdot \text{nm}}{400 \text{ nm}} = 3 \text{ eV}$$

$$K = E_{\varphi} - \varphi \Rightarrow K = 3 - 1,4 \Rightarrow K = 1,6 \text{ eV}$$

$$\text{Величина } K \rightarrow A \Rightarrow \Delta K = \Sigma W \Rightarrow K_A - K_K = q V_{KA} \Rightarrow$$

$$0 - K = -|e| V_{KA} \Rightarrow V_{KA} = \frac{K}{|e|} = \frac{1,6 \text{ eV}}{|e|} = 1,6 \text{ V}$$

ΘΕΜΑ Δ



Δ1. Παβδος ισορροπία άρα $\Sigma F = 0$

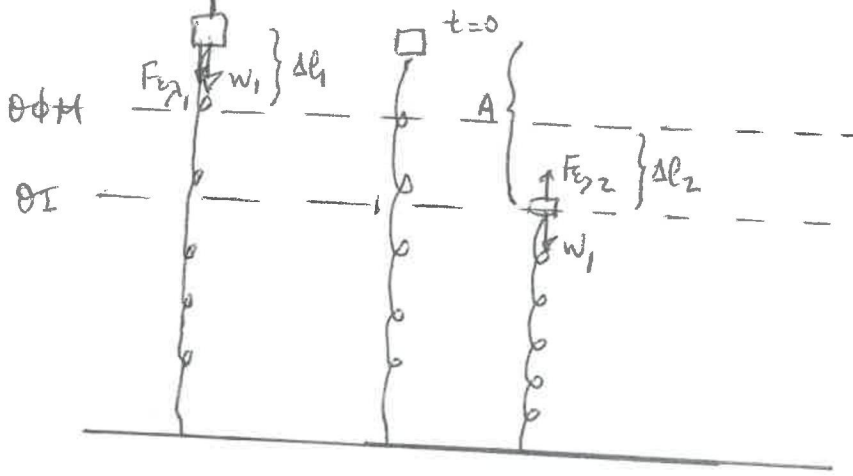
$$F = T + w_2 \Rightarrow 3 = T + 1 \Rightarrow T = 2N$$

Σw και m_1 ισορροπία άρα

$$\Sigma F = 0 \rightarrow T = F_{\epsilon\gamma 1} + w_1 \Rightarrow$$

$$2 = k \Delta l_1 + 1 \rightarrow 10 \Delta l_1 = 1 \Rightarrow \Delta l_1 = 0,1m$$

Κοβερνι το νημα



Σw και $\Sigma F = 0$

$$F_{\epsilon\gamma 2} = w_1 \Rightarrow$$

$$k \Delta l_2 = m_1 g \rightarrow$$

$$\Delta l_2 = \frac{m_1 g}{k} \rightarrow$$

$$\Delta l_2 = \frac{1}{10} = 0,1m$$

Ενναι $A = \Delta l_1 + \Delta l_2 \rightarrow A = 0,2m$

$$D = k \Rightarrow m_1 \omega^2 = k \Rightarrow \omega = \sqrt{\frac{k}{m_1}} = 10 \text{ rad/s}$$

$$x = A \eta \mu(\omega t + \varphi_0) \xrightarrow[t=A]{t=0} A = A \eta \mu \varphi_0 \Rightarrow \eta \mu \varphi_0 = 1 \rightarrow \varphi_0 = \frac{\pi}{2}$$

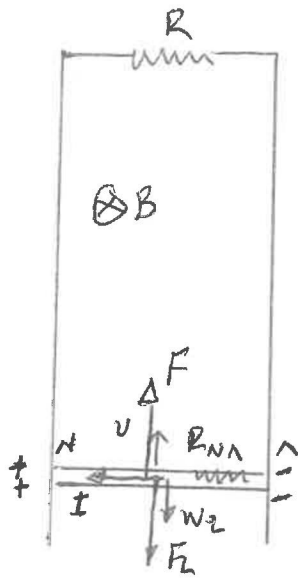
άρα $x = 0,2 \eta \mu(10t + \frac{\pi}{2})$ (SI)

Δ2. Ενναι $k = \frac{3}{4} E$ άρα $U = \frac{1}{4} E \Rightarrow$

$$\frac{1}{2} k x^2 = \frac{1}{4} \frac{1}{2} k A^2 \Rightarrow x^2 = \frac{A^2}{4} \Rightarrow |x| = \frac{A}{2} = 0,1m$$

$$\Sigma F = m a \Rightarrow -k x = m a \Rightarrow |a| = \frac{k}{m} |x| \Rightarrow$$

$$|a| = \omega^2 |x| = 100 \cdot 0,1 \Rightarrow |a| = 10 \text{ m/s}^2$$



$$\Delta 3. \quad \mathcal{E}_{\text{ind}} \quad \mathcal{E}_{\text{em}} = Bvl$$

$$I = \frac{\mathcal{E}_{\text{em}}}{R_{\text{tot}}} = \frac{Bvl}{R + R_{\text{rod}}} \quad (1)$$

$$\sum F = m_2 a \rightarrow F - F_L - w_2 = m_2 a \Rightarrow$$

$$a = \frac{F - BIl - m_2 a}{m} \quad (2)$$

$$\text{O60 } \vec{v} \uparrow \Rightarrow \vec{I} \uparrow \Rightarrow \vec{a} \downarrow$$

Δx ευρισκει μιζαxωομενη με ενιζαxωομη
 που το περικοπη μιζαxωομενη

$$v_{\text{op}} \text{ οταν } \sum F = 0 \Rightarrow F = w_2 + F_L \rightarrow$$

$$F - m_2 g = BIl \quad (1) \Rightarrow F - m_2 g = B \frac{Bv_{\text{op}} l}{R + R_{\text{rod}}} l \rightarrow$$

$$v_{\text{op}} = \frac{(F - m_2 g)(R + R_{\text{rod}})}{B^2 l^2} = \frac{(3-1)(1+1)}{1} \Rightarrow v_{\text{op}} = 4 \text{ m/s}$$

$$\Delta 4. \quad \mathcal{E}_{\text{ind}} \quad h = v_{\text{op}} \Delta t = 4 \cdot \frac{1}{8} = 0,5 \text{ m}$$

$$W_f = F \cdot h = 3 \cdot 0,5 = 1,5 \text{ J}$$

$$(1) \Rightarrow I = \frac{Bv_{\text{op}} l}{R + R_{\text{rod}}} = \frac{4}{2} = 2 \text{ A}$$

$$Q = I^2 (R + R_{\text{rod}}) \cdot \Delta t = 2^2 \cdot 2 \cdot \frac{1}{8} \Rightarrow Q = 1 \text{ J}$$

$$\Pi = \frac{Q}{W_f} \cdot 100\% = \frac{1}{1,5} \cdot 100\% \Rightarrow \Pi = \frac{200}{3} \%$$